

A SAMPLING KACZMARZ-MOTZKIN ALGORITHM FOR LINEAR FEASIBILITY

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ICCOPT
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Joint work with Jesus De Loera and Deanna Needell

LINEAR FEASIBILITY PROBLEM

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These problems arise in machine learning classification, *support-vector machines* (Boser, Guyon, Vapnik 1992), (Cortes, Vapnik 1995).

PROJECTION METHODS

If $P := \{x \in \mathbb{R}^n : Ax \leq b\}$ is nonempty, these methods construct an approximation to an element of P :

1. Motzkin's Relaxation Method(s)
2. Randomized Kaczmarz Method
3. Sampling Kaczmarz-Motzkin Method (SKM)

MOTZKIN'S RELAXATION METHOD(S)

Given $x_0 \in \mathbb{R}^n$, fix $0 < \lambda \leq 2$ and iteratively construct approximations to P :

1. If x_k is feasible, stop.
2. Choose $i_k \in [m]$ as $i_k := \operatorname{argmax}_{i \in [m]} a_i^T x_{k-1} - b_i$.
3. Define $x_k := x_{k-1} - \lambda \frac{a_{i_k}^T x_{k-1} - b_{i_k}}{\|a_{i_k}\|^2} a_{i_k}$.
4. Repeat.

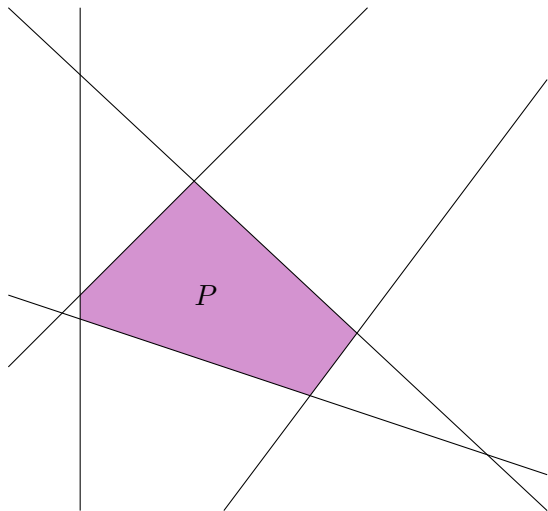
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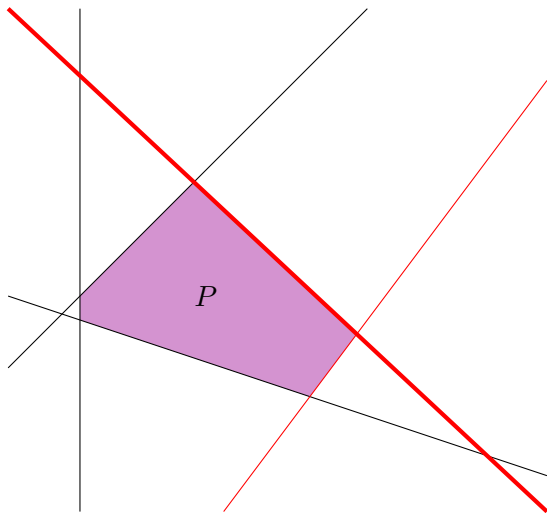
λ is the *projection (or relaxation) parameter*

MOTZKIN'S METHOD



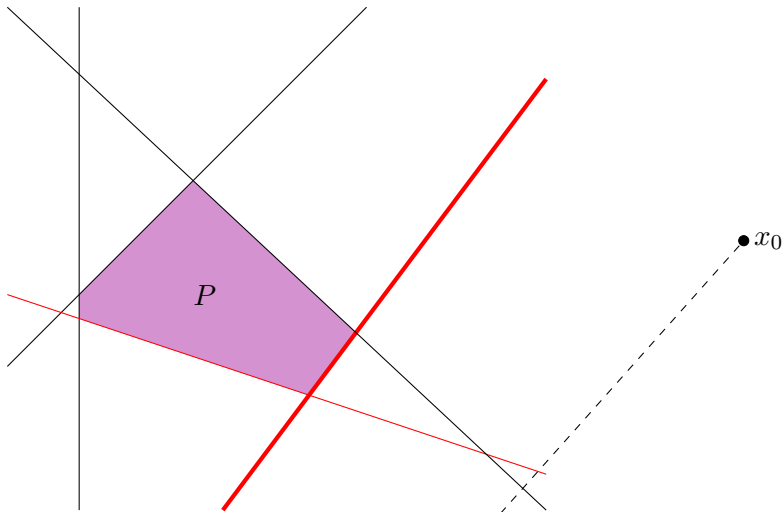
● x_0

MOTZKIN'S METHOD



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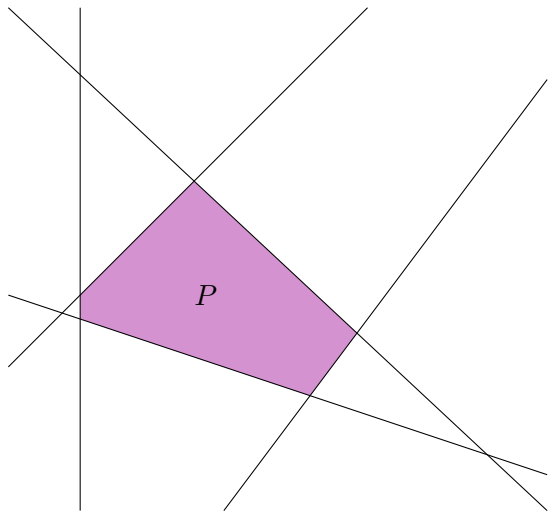


RANDOMIZED KACZMARZ METHOD

Given $x_0 \in \mathbb{R}^n$, iteratively construct approximations to P :

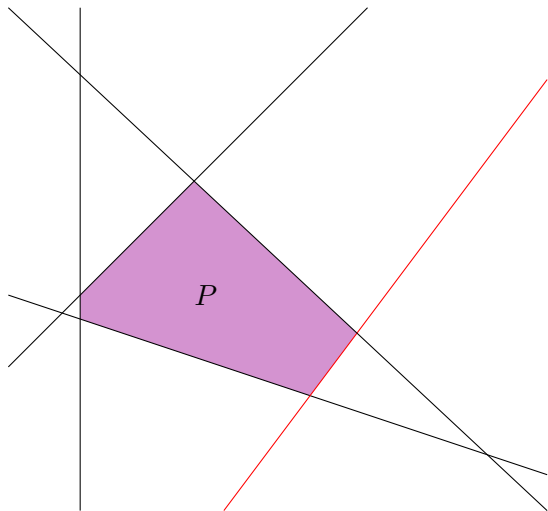
1. If x_k is feasible, stop.
2. Choose $i_k \in [m]$ with probability $\frac{\|a_{i_k}\|^2}{\|A\|_F^2}$.
3. Define $x_k := x_{k-1} - \frac{(a_{i_k}^T x_{k-1} - b_{i_k})^+}{\|a_{i_k}\|^2} a_{i_k}$.
4. Repeat.

KACZMARZ METHOD

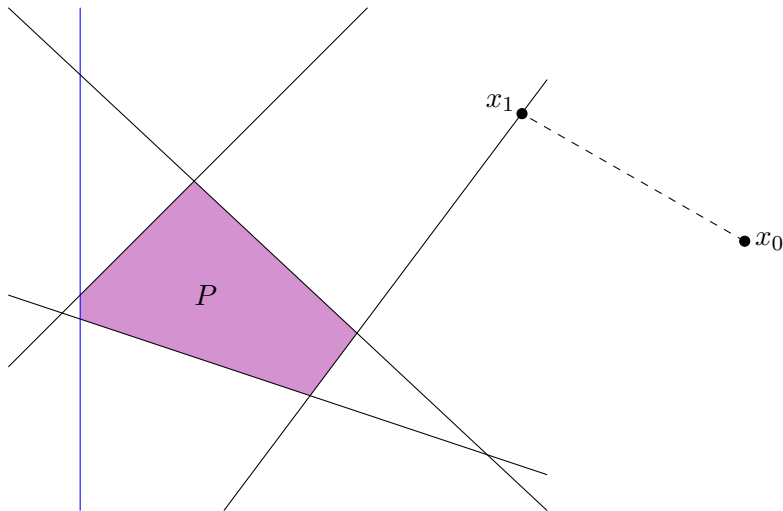


● x_0

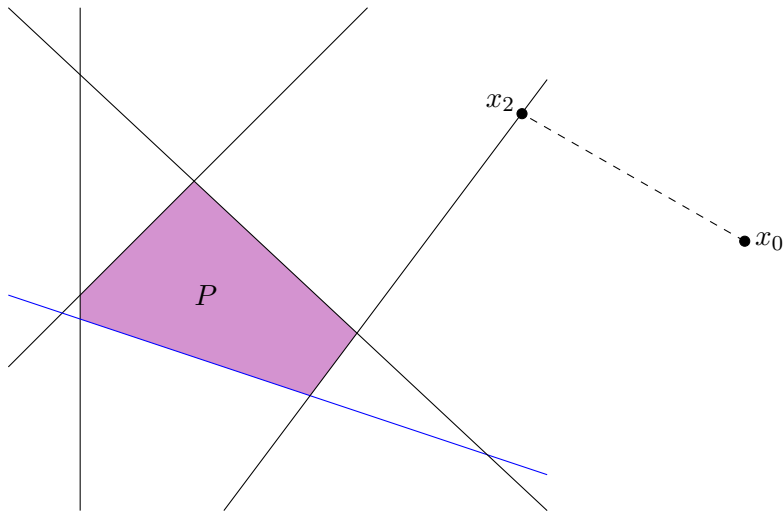
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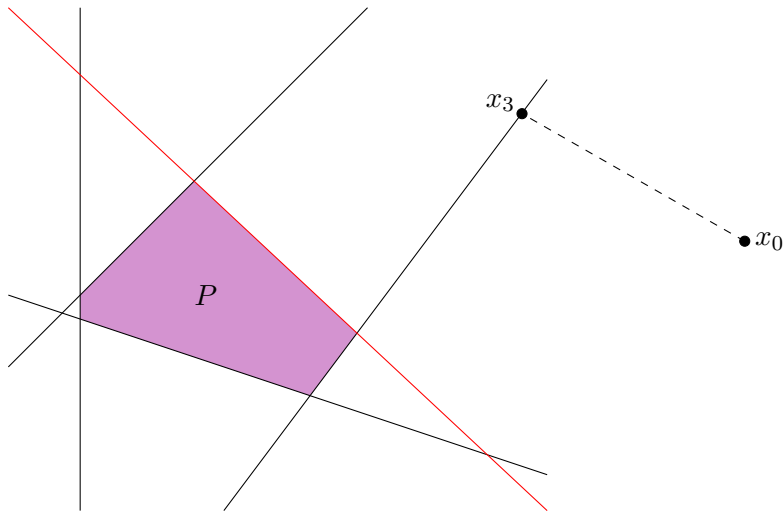
KACZMARZ METHOD



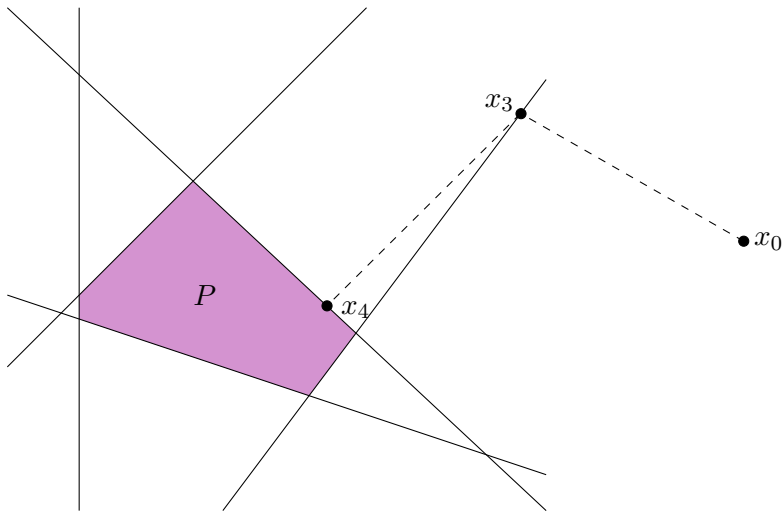
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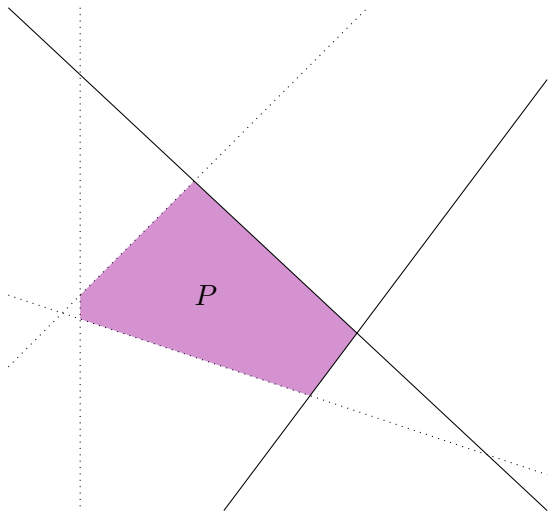
A HYBRID METHOD (SKM)

Given $x_0 \in \mathbb{R}^n$, fix $0 < \lambda \leq 2$ and iteratively construct approximations to P in the following way:

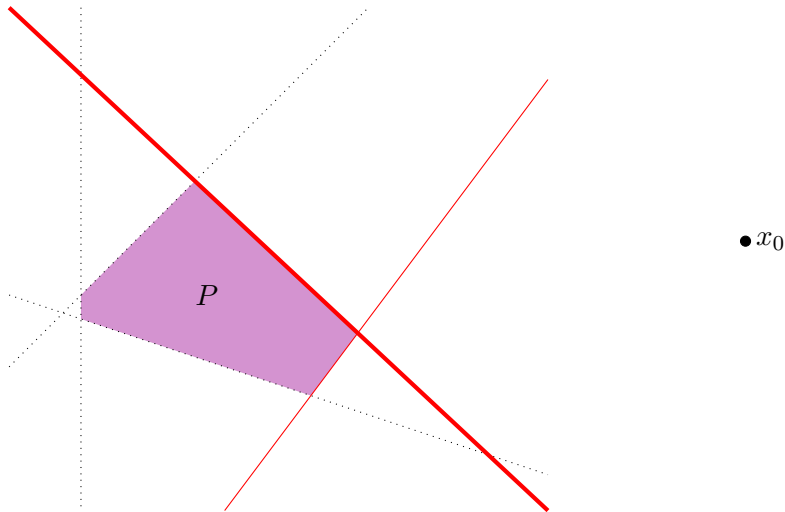
1. If x_k is feasible, stop.
2. Choose $\tau_k \subset [m]$ to be a sample of size β constraints chosen uniformly at random from among the rows of A .
3. From among these β rows, choose

$$i_k := \operatorname{argmax}_{i \in \tau_k} a_i^T x_{k-1} - b_i.$$
4. Define $x_k := x_{k-1} - \lambda \frac{(a_{i_k}^T x_{k-1} - b_{i_k})^+}{\|a_{i_k}\|^2} a_{i_k}$.
5. Repeat.

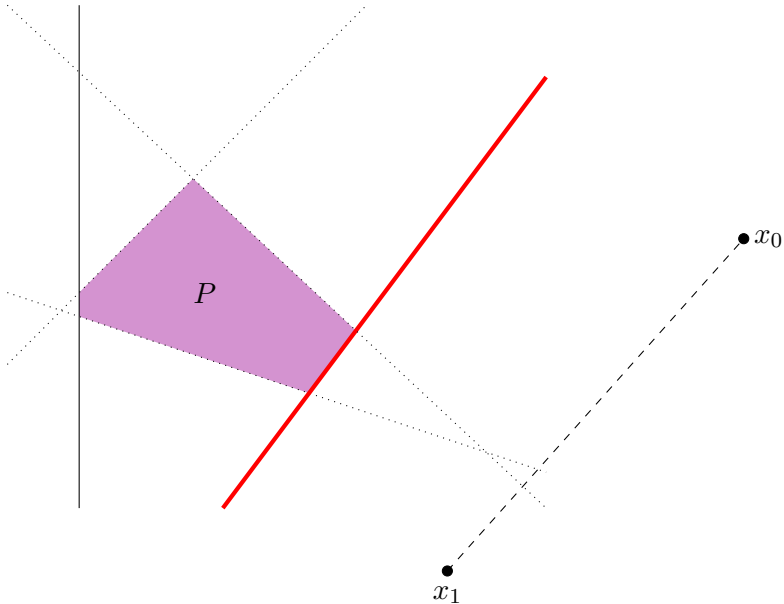
A HYBRID METHOD



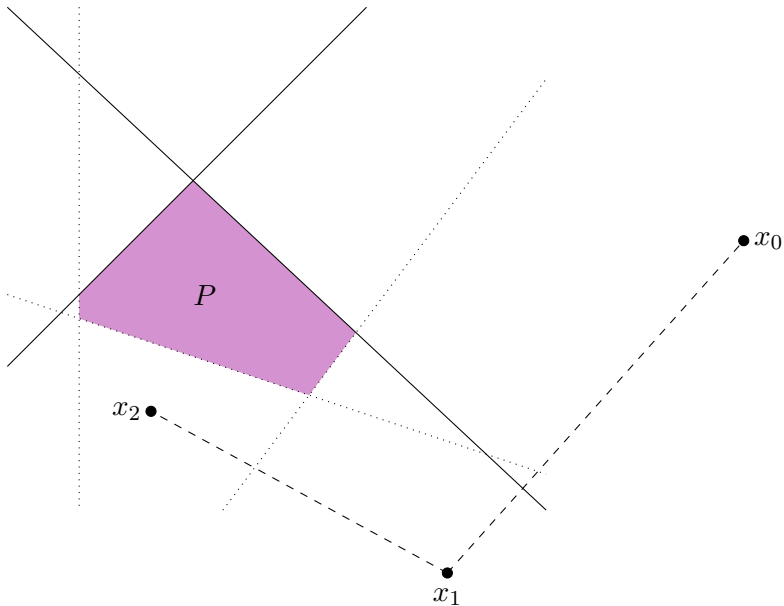
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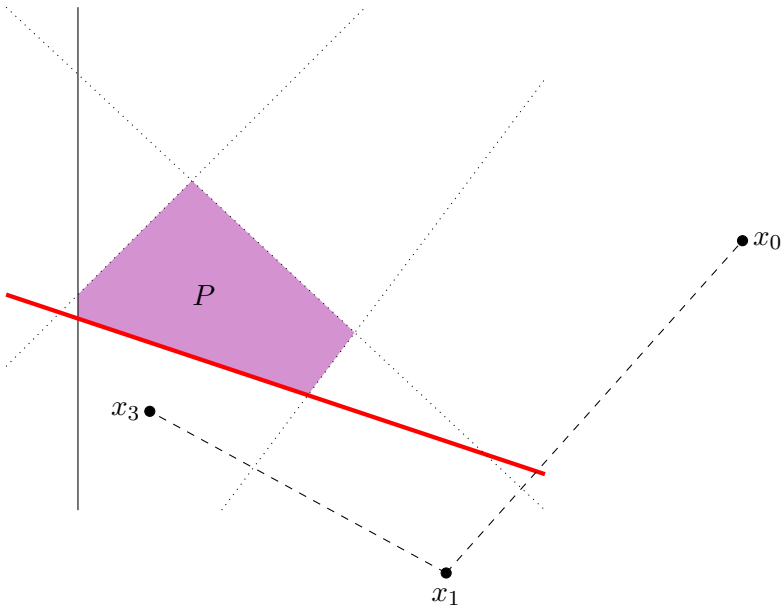
A HYBRID METHOD



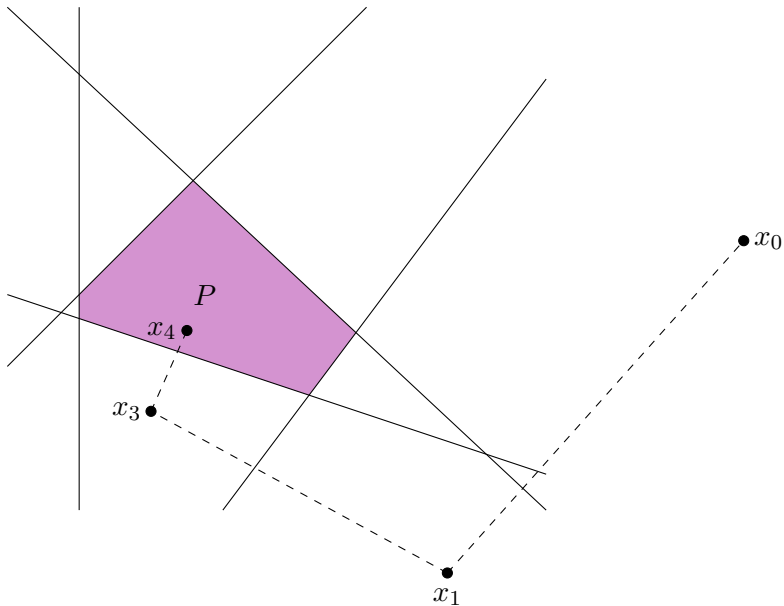
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SKM METHOD CONVERGENCE RATE

THEOREM (DE LOERA, H., NEEDELL)

If the feasible region (for row-normalized A) is nonempty, then the SKM methods with samples of size β converge at least linearly in expectation: If s_{k-1} is the number of constraints satisfied by x_{k-1} and $V_{k-1} = \max\{m - s_{k-1}, m - \beta + 1\}$ then

$$\begin{aligned} \mathbb{E}[d(x_k, P)^2] &\leq \left(1 - \frac{2\lambda - \lambda^2}{V_{k-1}L_2^2}\right) d(x_{k-1}, P)^2 \\ &\leq \left(1 - \frac{2\lambda - \lambda^2}{mL_2^2}\right)^k d(x_0, P)^2. \end{aligned}$$

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The *Hoffman constant*, L_2 is an error bound defined as the minimum constant that satisfies

$$d(x, P) \leq L_2 \| (Ax - b)^+ \|_2.$$

IMPROVED RATE

THEOREM (DE LOERA, H., NEEDELL)

If the feasible region, $P = \{x \mid Ax \leq b\}$ is nondegenerate (generic) and nonempty (for normalized A), then an SKM method with samples of size $\beta \leq m - n$ is guaranteed an increased convergence rate after some K :

$$\mathbb{E}[d(x_k, P)^2] \leq \left(1 - \frac{2\lambda - \lambda^2}{mL_2^2}\right)^K \left(1 - \frac{2\lambda - \lambda^2}{(m - \beta + 1)L_2^2}\right)^{k-K} d(x_0, P)^2.$$

FINITENESS OF MOTZKIN'S METHOD

THEOREM (GOFFIN 1980, TELGEN 1982)

Suppose A, b are rational matrices with binary encoding length σ , and that we run a relaxation method on the normalized system $\tilde{A}x \leq \tilde{b}$ with $x_0 = 0$. Then either the relaxation method detects feasibility of the system within $k = \left\lceil \frac{2^{4\sigma}}{n\lambda(2-\lambda)} \right\rceil$ iterations or the system is infeasible.

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The *binary encoding length* of the problem is

$$\sigma = \sum_{i=1}^m \sum_{j=1}^n \log(|a_{ij}| + 1) + \sum_{i=1}^m \log(|b_i| + 1) + \log(nm) + 2.$$

CERTIFICATES OF FEASIBILITY

Define the *maximum violation* in the point x to be

$$\theta(x) := \max\{0, \max_{i \in [m]} a_i^T x - b_i\}.$$

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If the rational system $Ax \leq b$ (with binary encoding length σ) is infeasible, then for all $x \in \mathbb{R}^n$, the maximum violation satisfies $\theta(x) \geq 2^{1-\sigma}$.

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LEMMA

If the rational system $Ax \leq b$ (with binary encoding length σ) is infeasible, then for all $x \in \mathbb{R}^n$, the maximum violation satisfies $\theta(x) \geq 2^{1-\sigma}$.

Thus, to detect feasibility of the rational system $Ax \leq b$, we need only find a point, x_k with $\theta(x_k) < 2 * 2^{-\sigma}$; such a point will be called a *certificate of feasibility*.

EXPECTED FINITENESS OF SKM METHODS

THEOREM (DE LOERA, H., NEEDELL)

Suppose A, b are rational matrices with binary encoding length σ , and that we run an SKM method on the normalized system $\tilde{A}x \leq \tilde{b}$ with $x_0 = 0$. Suppose the number of iterations k satisfies

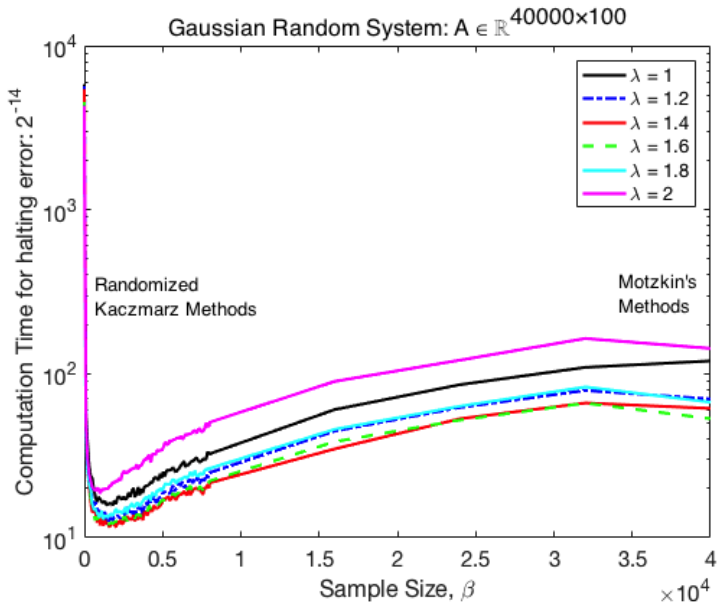
$$k > \frac{4\sigma - 4 - \log n + 2 \log \left(\max_{j \in [m]} \|a_j\| \right)}{\log \left(\frac{mL_2^2}{mL_2^2 - 2\lambda + \lambda^2} \right)}.$$

If the system $Ax \leq b$ is feasible, the probability that the iterate x_k is not a certificate of feasibility is at most

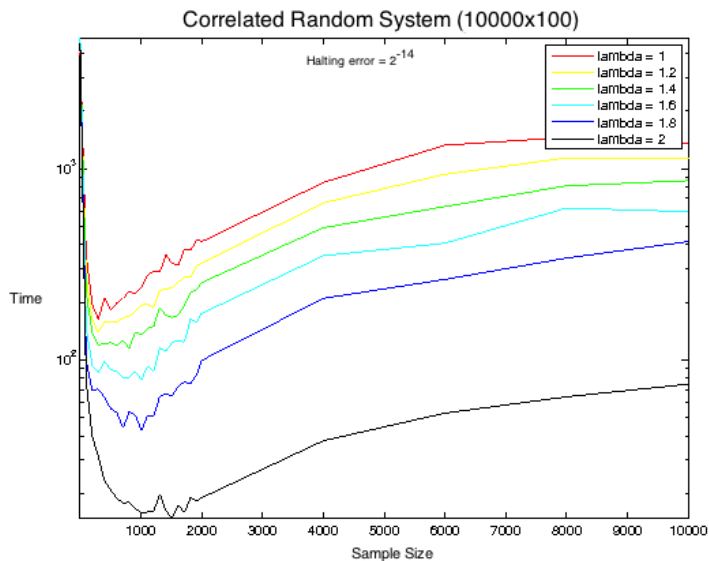
$$\frac{\max \|a_j\|}{n^{1/2}} 2^{2\sigma-2} \left(1 - \frac{2\lambda - \lambda^2}{mL_2^2} \right)^{k/2},$$

which decreases with k .

EXPERIMENTAL RESULTS

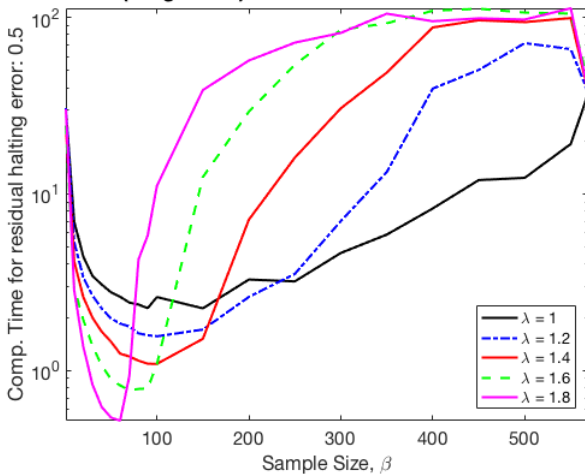


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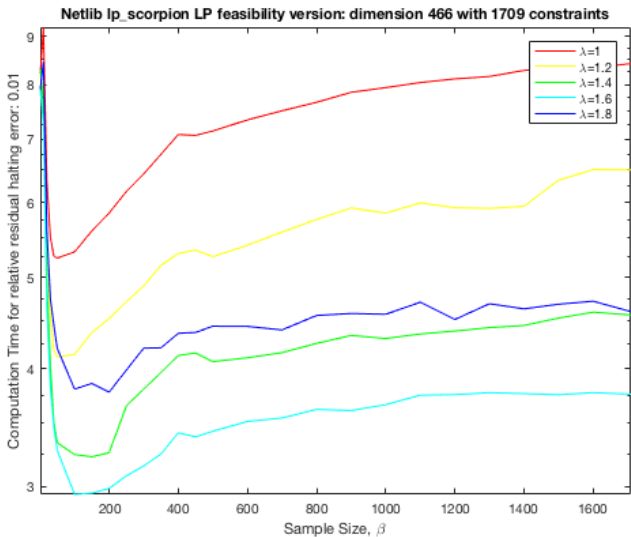


EXPERIMENTAL RESULTS

Wisconsin (Diagnostic) Breast Cancer SVM Data Set: 569 x 30



EXPERIMENTAL RESULTS



ACKNOWLEDGEMENTS

Thanks to you for attending!

Are there any questions?

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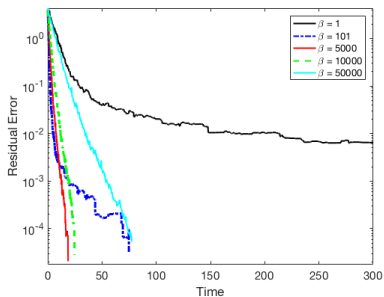
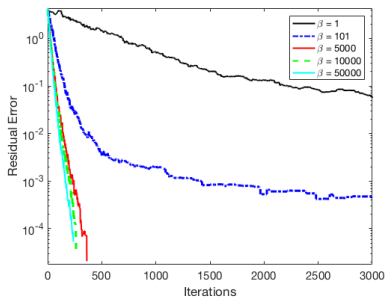
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ITERATIONS VS. TIME



SKM on Gaussian random system, $A \in \mathbb{R}^{50000 \times 100}$

HEURISTICS FOR β SELECTION

In an iteration, the expected improvement is

$$d(x_j, P)^2 - d(x_{j+1}, P)^2 = \mathbb{E} \left[\|(A_{\tau_j} x_j - b_{\tau_j})^+\|_{\infty}^2 \right].$$

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We consider this case and model the computation in a fixed iteration as the overhead cost, C , and a factor $cn\beta$ for checking the feasibility of β constraints.

HEURISTICS FOR β SELECTION

Note that

$$\mathbb{E}\left[\|(A_{\tau_j}x_j - b_{\tau_j})^+\|_{\infty}^2\right] = \begin{cases} 1 - \frac{\binom{s}{\beta}}{\binom{m}{\beta}} \approx 1 - \left(\frac{s}{m}\right)^{\beta} & \text{if } \beta \leq s \\ 1 & \text{if } \beta > s \end{cases}$$

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Thus, we look for β that maximizes the improvement per unit of computation time:

$$\text{gain}(\beta) := \frac{\mathbb{E}\left[\|(A_{\tau_j}x_j - b_{\tau_j})^+\|_{\infty}^2\right]}{C + cn\beta} \approx \frac{1 - \left(\frac{s}{m}\right)^{\beta}}{C + cn\beta}.$$

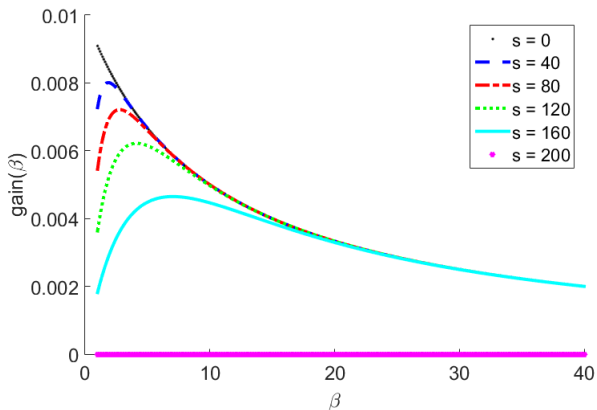


FIGURE : The quantity $\text{gain}(\beta)$ as a function of β for various numbers of satisfied constraints s . Here we set $m = 200$, $n = 10$, $c = 1$ and $C = 100$. Optimal values of β maximize the gain function.