

Greedy and Randomized Projection Methods

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UCLA CAM Colloquium,

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Computational and Applied Mathematics

UCLA



joint with Jesús A. De Loera, Deanna Needell, and Anna Ma
<https://arxiv.org/abs/1802.03126> (BIT Numerical Mathematics 2019)
<https://arxiv.org/abs/1605.01418> (SISC 2017)

The big data opportunity



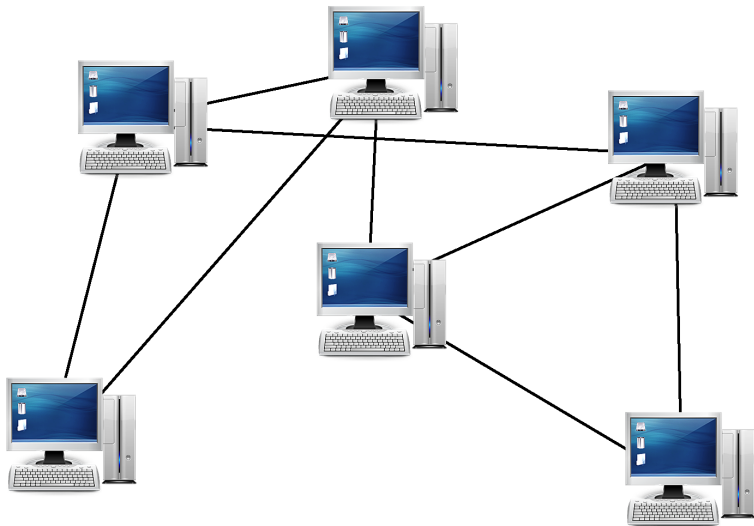
DellWorld^{YS}

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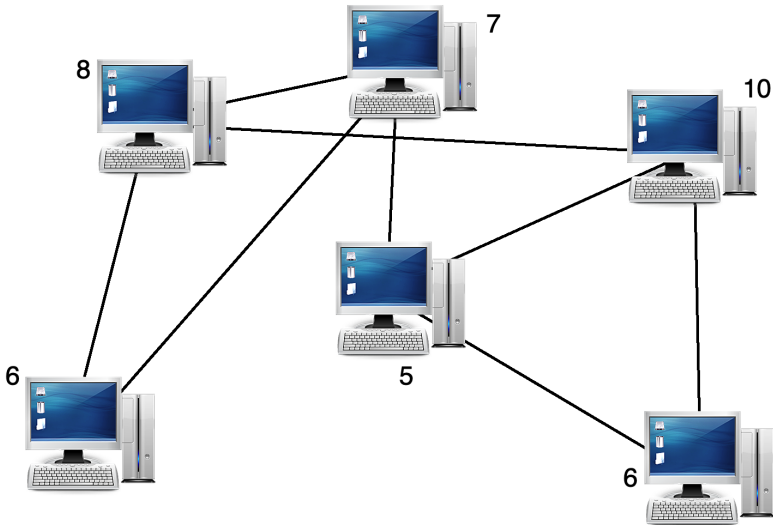




Motivation: Average Consensus

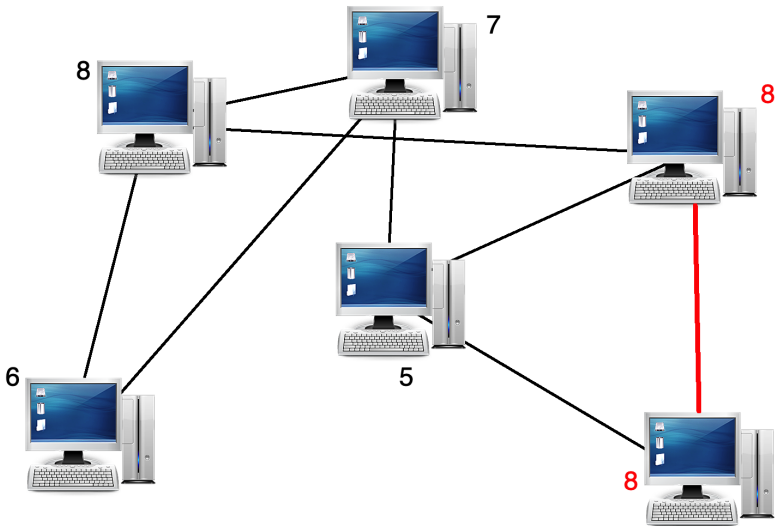


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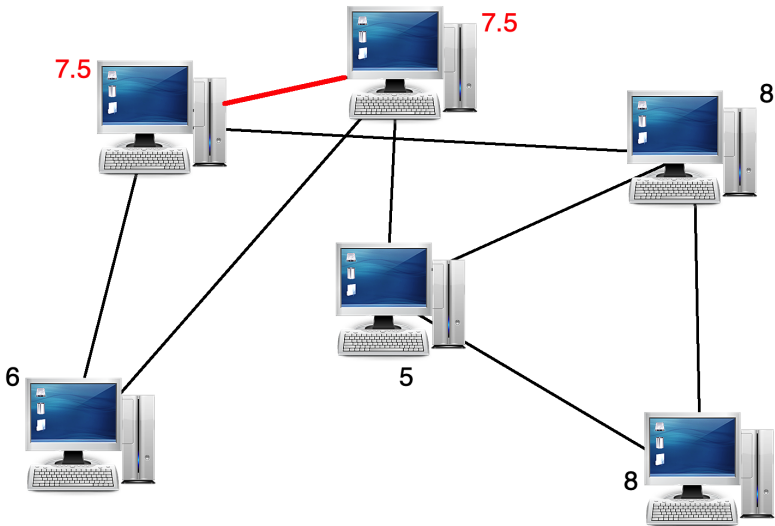
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Gossip Method: Begin with $\mathbf{x}_0 = \mathbf{c} \in \mathbb{R}^{|\mathcal{V}|}$:

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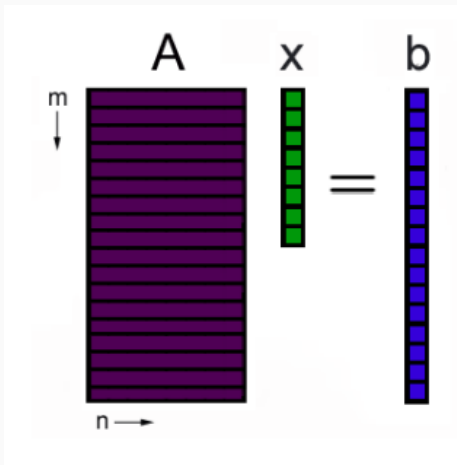
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- ▷ clock synchronization
- ▷ PageRank
- ▷ opinion formation
- ▷ blockchain technology

General Setup

We are interested in solving **highly overdetermined systems of equations (or inequalities)**, $Ax = b$ ($Ax \leq b$), where $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ and $m \gg n$. Rows are denoted $\mathbf{a}_i^T$.



Iterative Projection Methods

If $\{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = \mathbf{b}\}$ is nonempty, these methods construct an **approximation** to a solution:

1. Randomized Kaczmarz Method



Applications:

1. Tomography (Algebraic Reconstruction Technique)

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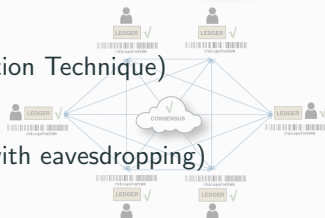
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3. Sampling Kaczmarz-Motzkin Methods (SKM)



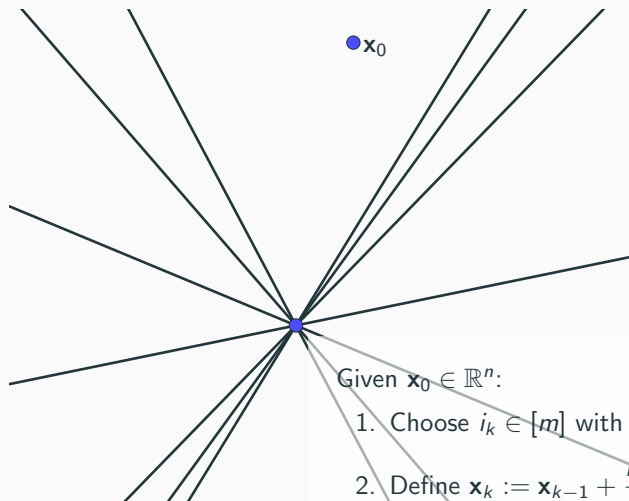
Applications:

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2. Linear programming
3. Average consensus (greedy gossip with eavesdropping)

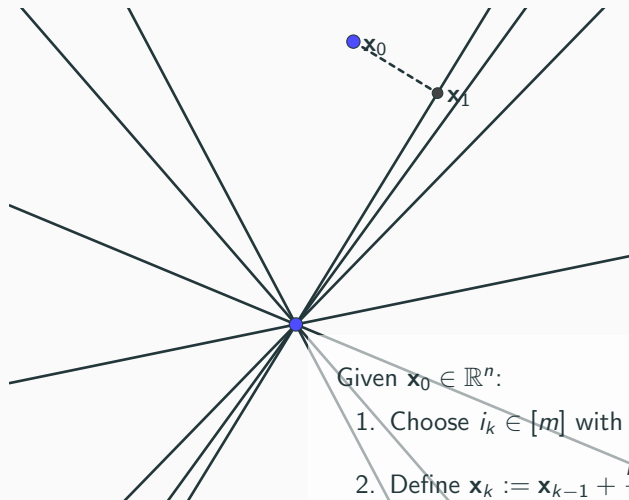


When all node operators agree to the change and consensus is reached, the entire network will update their own ledgers. This ensures the immutability of records for network participants and end-users.

Kaczmarz Method



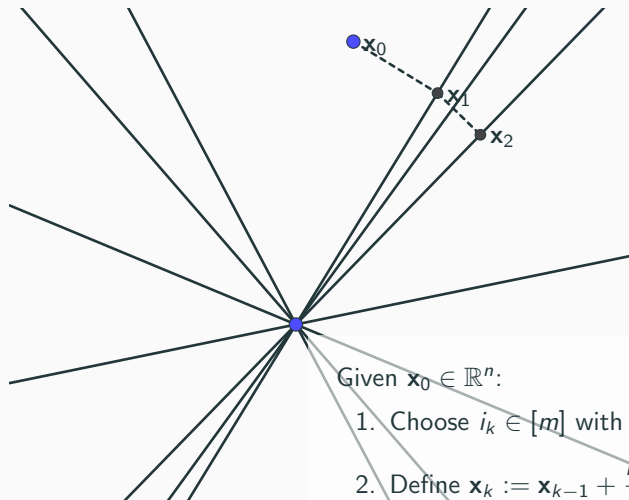
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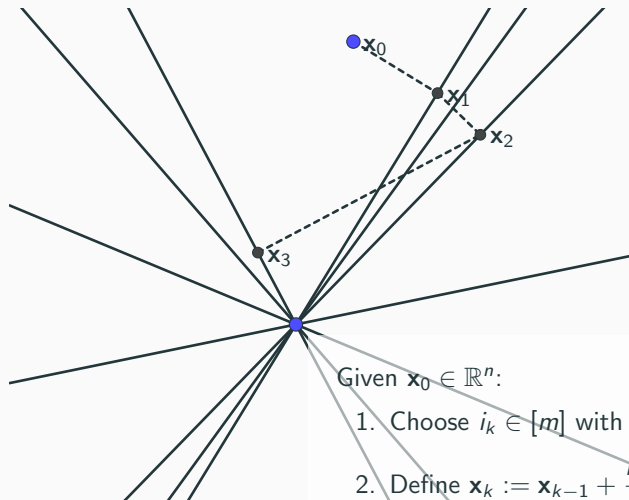
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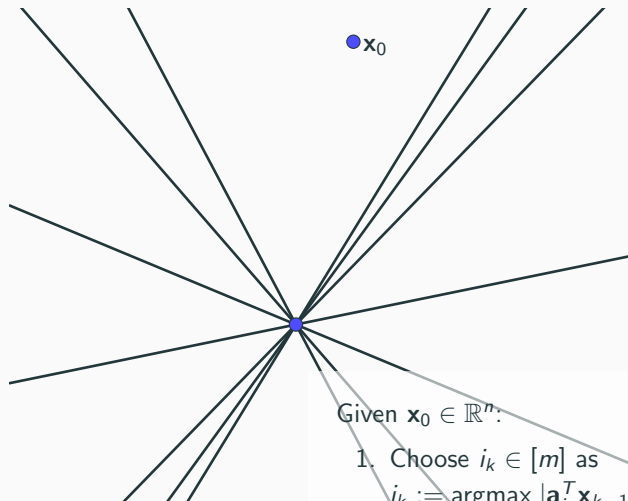
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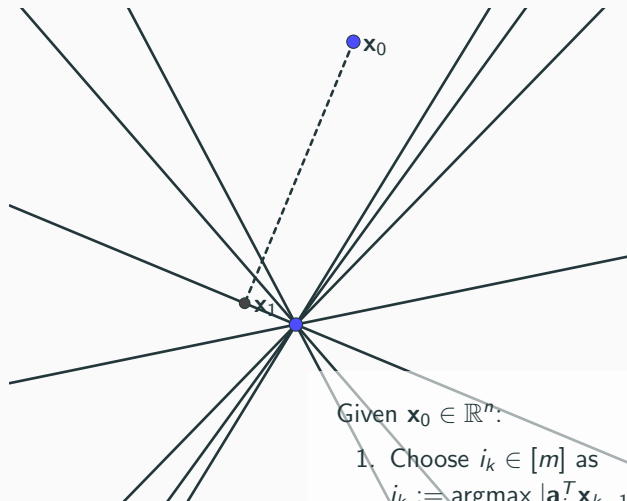
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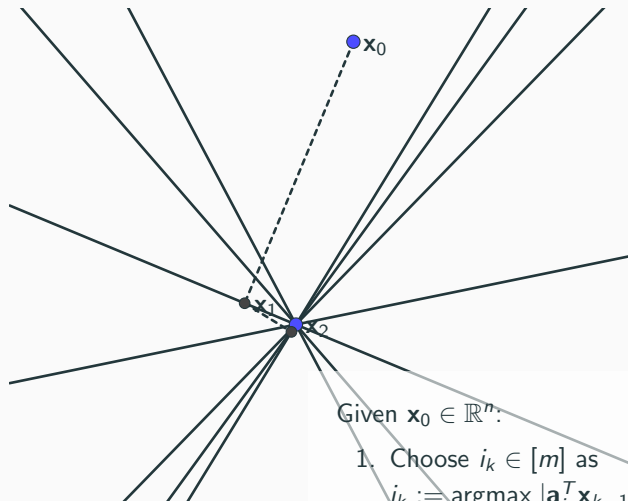
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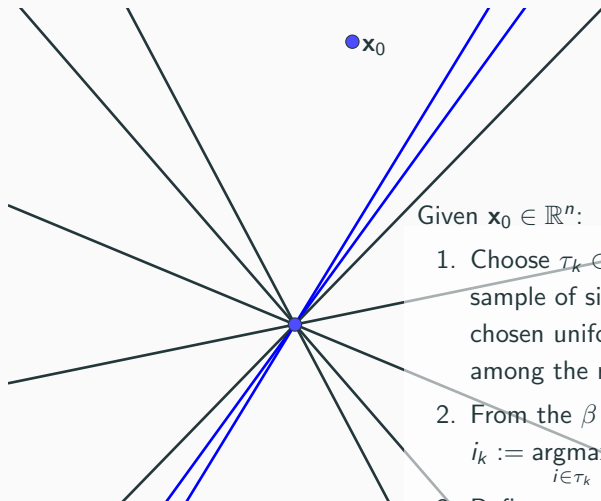
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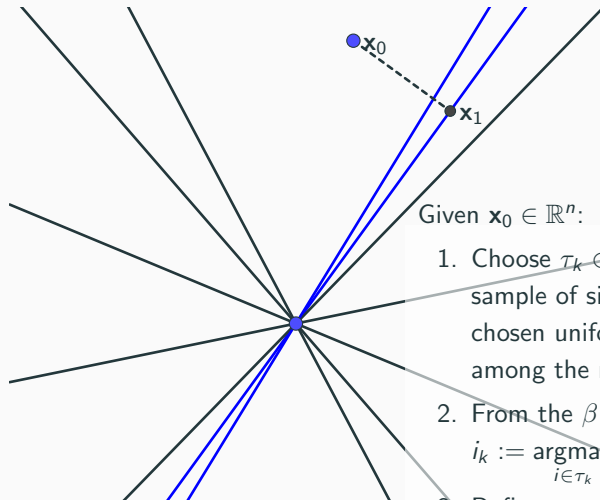
Our Hybrid Method (SKM)



Given $\mathbf{x}_0 \in \mathbb{R}^n$:

1. Choose $\tau_k \in [m]$ to be a sample of size β constraints chosen uniformly at random among the rows of A .
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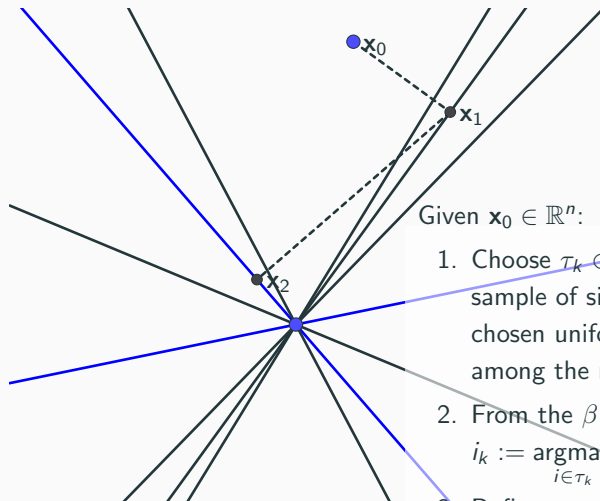
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Glimpse of HUGE Body of Literature

RK: [Strohmer-Vershynin '09], [Needell-Srebro-Ward '16]

Greedy: [Censor '81], [Nutini et al '16], [Bai-Wu '18], [Du-Gao '19]

Accel.: [Hanke-Niethammer '90], [Liu-Wright '16], [Morshed-Islam '19]

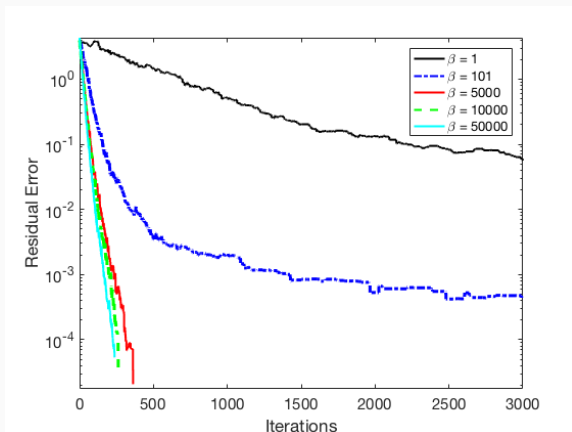
Block: [Popa et al '12], [Needell-Tropp '14], [Needell-Zhao-Zouzias '15],

Sketching: [Gower-Richtarik '15], [Needell-Rebrova '19]

Phase retrieval: [Tan-Vershynin '17], [Jeong-Güntürk '17]

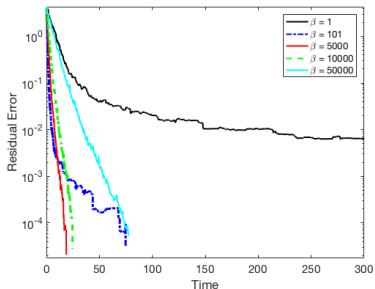
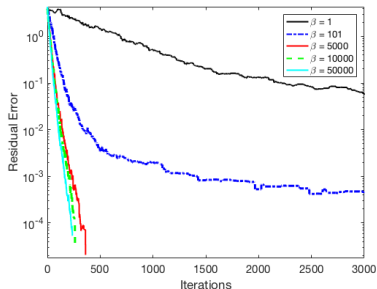
LP: [Motzkin-Schoenberg '54], [Agmon '54], [Goffin '80], [Chubanov '12]

Experimental Convergence



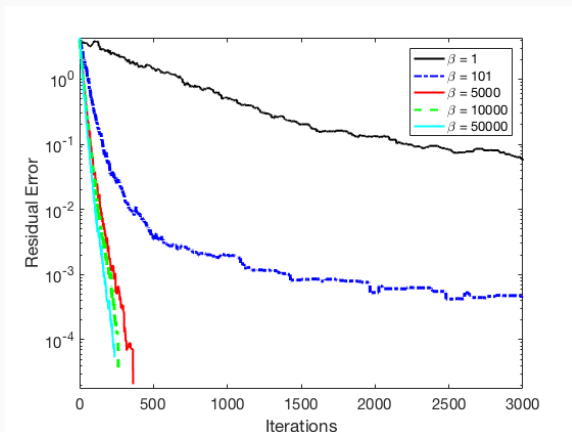
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Convergence Rates

Below are the convergence rates for the methods on a system, $A\mathbf{x} = \mathbf{b}$, which is consistent with unique solution $\mathbf{x}$, whose rows have been normalized to have unit norm.

▷ RK (Strohmer - Vershynin '09):

$$\mathbb{E} \|\mathbf{x}_k - \mathbf{x}\|_2^2 \leq \left(1 - \frac{\sigma_{\min}^2(A)}{m}\right)^k \|\mathbf{x}_0 - \mathbf{x}\|_2^2$$

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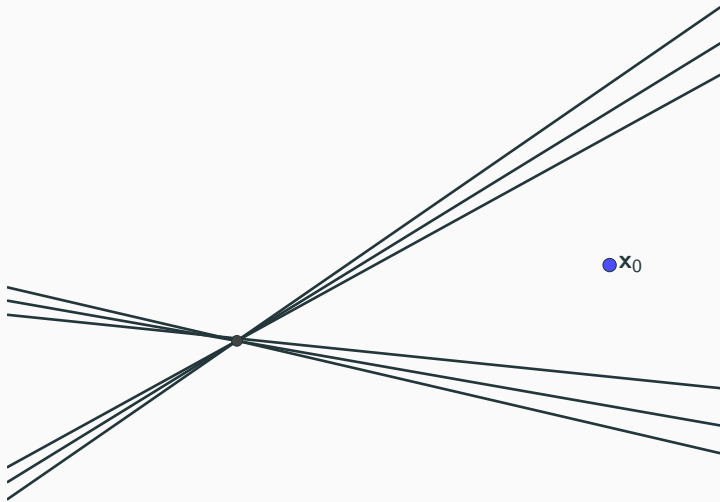
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Why are these all the same?

A Pathological Example

Because.



Structure of the Residual

Several works have used sparsity of the residual to improve the convergence rate of greedy methods.

[De Loera, H., Needell '17], [Bai, Wu '18], [Du, Gao '19]

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However, not much sparsity can be expected in most cases. Instead, we'd like to use dynamic range of the residual to guarantee faster convergence.

$$\gamma_k := \frac{\|A\mathbf{x}_k - A\mathbf{x}\|^2}{\|A\mathbf{x}_k - A\mathbf{x}\|_\infty^2}$$

An Accelerated Convergence Rate

Theorem (H. - Needell '19)

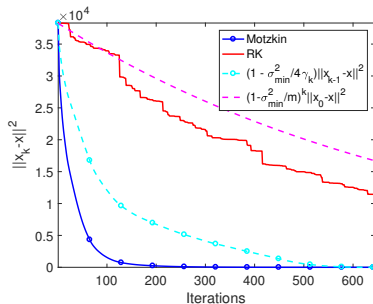
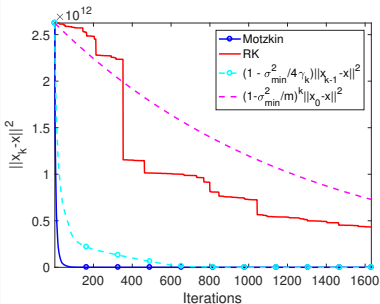
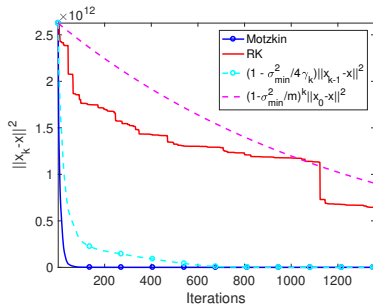
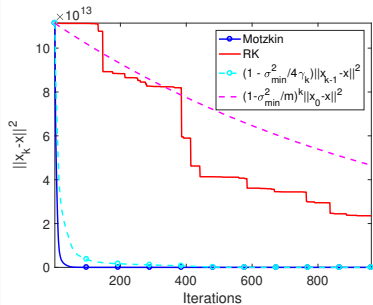
Let $\mathbf{x}$ denote the solution of the consistent, normalized system $A\mathbf{x} = \mathbf{b}$.
Motzkin's method exhibits the (possibly highly accelerated) convergence rate:

$$\|\mathbf{x}_T - \mathbf{x}\|^2 \leq \prod_{k=0}^{T-1} \left(1 - \frac{\sigma_{\min}^2(A)}{4\gamma_k} \right) \cdot \|\mathbf{x}_0 - \mathbf{x}\|^2$$

Here γ_k bounds the dynamic range of the k th residual, $\gamma_k := \frac{\|A\mathbf{x}_k - A\mathbf{x}\|^2}{\|A\mathbf{x}_k - A\mathbf{x}\|_\infty^2}$.

▷ improvement over previous result when $4\gamma_k < m$

Netlib LP Systems



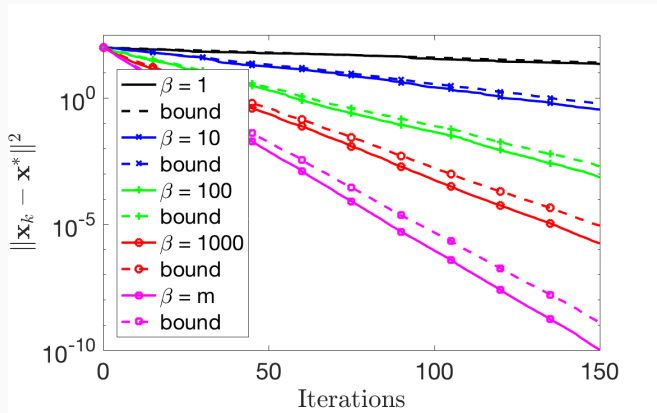
Corollary (H. - Ma 2019+)

Let A be normalized so $\|\mathbf{a}_i\|_2 = 1$ for all rows $i = 1, \dots, m$. If the system $A\mathbf{x} = \mathbf{b}$ is consistent with the unique solution $\mathbf{x}^$ then the SKM method converges at least linearly in expectation and the rate depends on the dynamic range of the random sample of rows of A , τ_j . Precisely, in the $j + 1$ st iteration of SKM, we have*

$$\mathbb{E}_{\tau_j} \|\mathbf{x}_{j+1} - \mathbf{x}^*\|_2^2 \leq \left(1 - \frac{\beta \sigma_{\min}^2(A)}{\gamma_j m}\right) \|\mathbf{x}_j - \mathbf{x}^*\|_2^2$$

$$\text{where } \gamma_j = \frac{\sum_{\tau_j \in \binom{[m]}{\beta}} \|A_{\tau_j} \mathbf{x}_j - \mathbf{b}_{\tau_j}\|_2^2}{\sum_{\tau_j \in \binom{[m]}{\beta}} \|A_{\tau_j} \mathbf{x}_j - \mathbf{b}_{\tau_j}\|_\infty^2}.$$

Extending to SKM



- ▷ A is 50000×100 Gaussian matrix, consistent system
- ▷ bound uses dynamic range of sample of β rows

What can we say about γ_j ?

$$1 \leq \gamma_j \leq \beta$$

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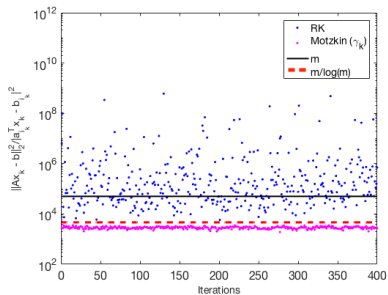
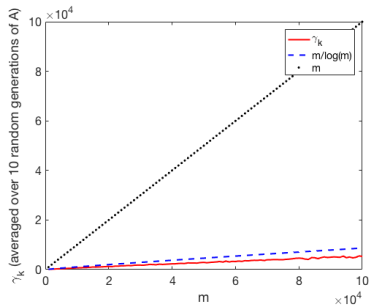
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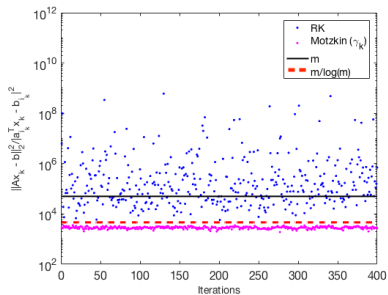
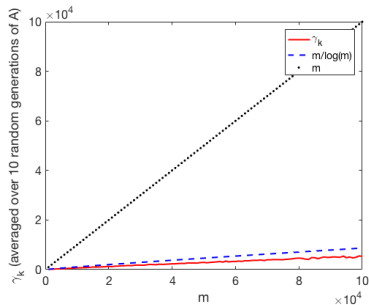
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$$\gamma_k \geq \frac{\beta}{m} \sigma_{\min}^2(A) \text{ when } A \text{ is row-normalized}$$

γ_k : Gaussian systems

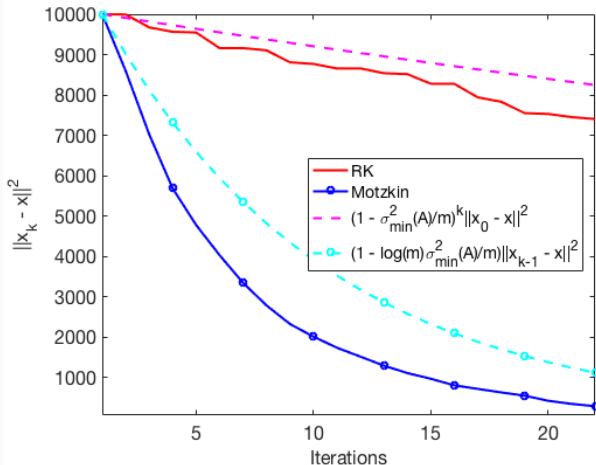


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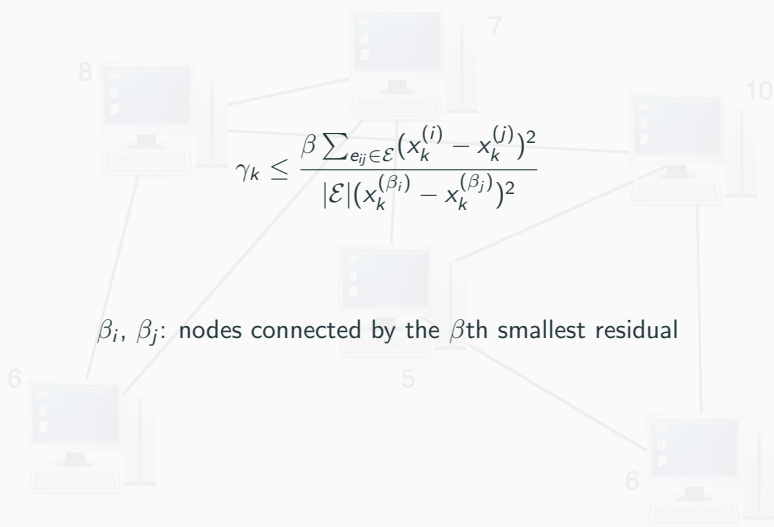


$$\gamma_k \lesssim \frac{n\beta}{\log \beta}$$

Gaussian Convergence



▷ A is 50000×100 Gaussian matrix, consistent system



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proportional to norm of selected row

Generalized SKM

Given $\mathbf{x}_0 \in \mathbb{R}^n$:

1. Choose $\tau_k \in \binom{[m]}{\beta_k}$ according to $p_{\mathbf{x}_{k-1}}$.
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Generalized Result

Theorem (H. - Ma 2019+)

Let $\mathbf{x}^*$ denote the unique solution to the system of equations $A\mathbf{x} = \mathbf{b}$. Then generalized SKM converges at least linearly in expectation and the bound on the rate depends on the dynamic range, γ_k of the random sample of β_k rows of A , τ_k . Precisely, in the k th iteration of generalized SKM, we have

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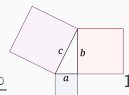
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▷ If all rows of A have the same norm, then

$$\mathbb{E}_{\tau_k} \|\mathbf{x}_k - \mathbf{x}^*\|^2 \leq \left(1 - \frac{\beta_k \sigma_{\min}^2(A)}{\gamma_k \|A\|_F^2} \right) \|\mathbf{x}_{k-1} - \mathbf{x}^*\|^2.$$

Sketch of Proof

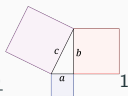
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¹Originally created by en:User:Michael Hardy, then scaled, with colour and labels being added by en:User:Wapcaplet, transformed in svg format by fr:Utilisateur:Steff, changed colors and font by de:Leo2004. (<https://commons.wikimedia.org/wiki/File:Pythagorean.svg>)

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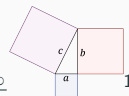


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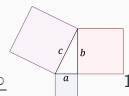


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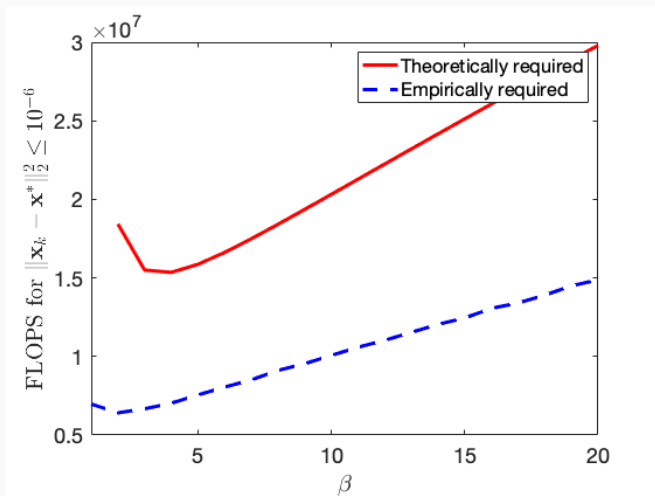
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Questions?

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